# Meeting 2

Date: 6 – Match – 2020

Agenda

* Current status of environment setup
* Questions about environment setup
* Distribution of tasks

## Attendance

* Professor Thomas Bräunl
* Oluwafemi Stephen Arowosafe
* Guangming Chen
* Yunzhuo Chen
* Gerardo Cisneros Mendoza
* Yuan Shi (Video call)
* Craig Brogle

## Glossary of terms and acronyms

CARLA - Open-source simulator for autonomous driving research.

ROS - Robot Operating System. A flexible framework for writing robot software.

## Minutes

* The project team have talked with Craig and Professor Thomas Bräunl about the environment setup.
* The project team explains the problems faced when setting up the environment.
* New tasks have been assigned to each member of the team:
  + Stephen: Start the modelling of the vehicle using a based model downloaded from a free source.
  + Gerardo: Research and start building the roads of the UWA campus to import them into CARLA.
  + Yunzhuo and Guangming: Start modelling the buildings of the UWA campus to import them into CARLA.
* Professor Thomas contacted Jay Jay Jegathesan who worked on modelling of some UWA areas and could share the models with to use it in the project.

## Attachments

No attachments included.